

Trichromatic Online Matching in Real-time Spatial Crowdsourcing

Tianshu Song¹, Yongxin Tong¹, Libin Wang¹, Jieying She², Bin Yao³, Lei Chen², Ke Xu¹

¹ SKLSDE Lab and IRI, Beihang University, China

² The Hong Kong University of Science and Technology, Hong Kong, China

³ Shanghai Jiao Tong University, China

¹{yxtong, songts, lbwang, kexu}@buaa.edu.cn, ²{jshe, leichen}@cse.ust.hk, ³yaobin@cs.sjtu.edu.cn

Introduction

- Spatial Crowdsourcing (a.k.a Mobile Crowdsourcing)
 - Online platforms that facilitate spatial tasks to be assigned and performed by crowd workers, e.g. O2O applications.

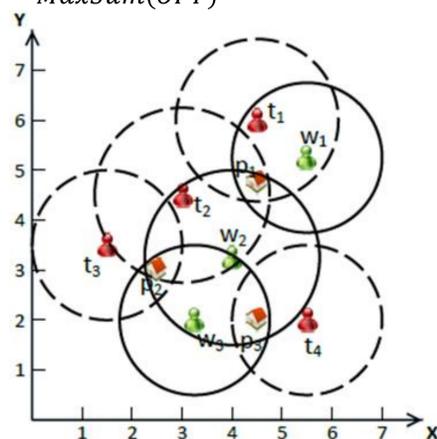


- Motivation
 - Most O2O platforms work on real-time scenarios.
 - Some emerging O2O applications need to assign three types of objects :
 - Sports trainers, sports facilities and users.
 - Hairstylists, salon and customers.

The GOMA Problem

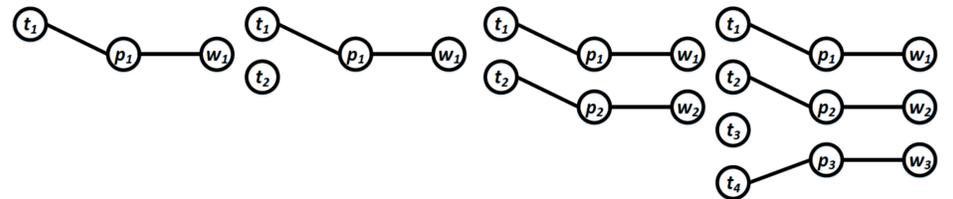
- Given
 - A set of tasks requester T
 - Each $t \in T$: location \mathbf{l}_t , arriving time b_t , leaving time e_t and range radius r_t .
 - A set of crowd workers W
 - Each $w \in W$: location \mathbf{l}_w , arriving time b_w , leaving time e_w , range radius r_w .
 - A set of crowd workplaces P
 - Each $p \in P$: location \mathbf{l}_p , arriving time b_p , leaving time e_p .
 - Utility Function: $U(t, p, w)$.
- Find a matching M to maximize the total utility $MaxSum(M) = \sum_{t \in T, p \in P, w \in W} U(t, p, w)$ s.t.
 - Deadline Constraint.
 - Range Constraint.
 - Invariable Constraint: *Once a task t is assigned to a worker w , the allocation of (t, p, w) cannot be changed.*
- Online Algorithm Evaluation: Competitive Ratio (CR)
 - Randomized Algorithm
 - $CR = \min_{\forall G(T, W, P, U)} \text{and } \forall v \in V \frac{\mathbb{E}[MaxSum(M)]}{MaxSum(OPT)}$

Object	Location	Arrival Time	Leaving Time
t_1	(4.50,6.00)	8:00	8:10
p_1	(4.50,4.75)	8:02	8:12
w_1	(5.50,5.00)	8:05	8:15
t_2	(3.00,4.50)	8:08	8:18
p_2	(2.50,3.00)	8:10	8:20
w_2	(4.00,3.25)	8:11	8:21
w_3	(3.25,2.00)	8:13	8:23
t_3	(1.50,3.50)	8:15	8:25
t_4	(5.50,2.00)	8:17	8:27
p_3	(4.50,2.00)	8:19	8:29



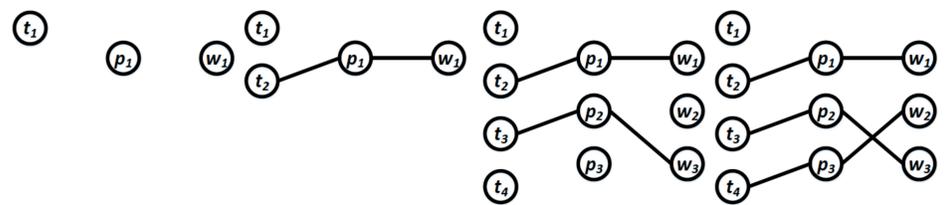
Match	Utility Score	Match	Utility Score
(t_1, p_1, w_1)	18	(t_2, p_2, w_3)	20
(t_1, p_1, w_2)	10	(t_3, p_2, w_2)	12
(t_2, p_1, w_1)	90	(t_3, p_2, w_3)	48
(t_2, p_1, w_2)	20	(t_4, p_3, w_2)	72
(t_2, p_2, w_2)	20	(t_4, p_3, w_3)	12

Greedy Algorithm



- Match all triples when it is possible
- Competitive Ratio: $CR = \frac{1}{3U_{max}}$

Basic-Threshold Algorithm



- Steps
 - Choose an integer k from 1 to $\lceil \ln(U_{max} + 1) \rceil$ randomly.
 - filter the edges with weights greater than e^k .
 - Use a greedy strategy on the remaining edges.
- Competitive Ratio: $CR = \frac{1}{3e^{\lceil \ln(U_{max} + 1) \rceil}}$

Adaptive-Threshold Algorithm

Threshold	t_1	w_1	t_2	w_2	t_3	p_3
e^0	1	1.02	1.02	1.04	1.04	1.05
e^1	1	1.02	1.02	1.04	1.04	1.05
e^2	1	1.02	1.02	1.04	1.04	1.05
e^3	1	1	1.09	1.09	1.14	1.22
e^4	1	1	1.09	1.09	1.09	1.17

- Adaptively adjust the probability distribution of choosing different thresholds.
- When an object appear, choose a new threshold according to the learned probability distribution
- $MaxSum \geq (1 - \epsilon)MaxSum(OPT_{Basic-Threshold}) - \frac{\epsilon(1-\epsilon)}{2D} \sum_v (g_v^*)^2 - \frac{D(1-\epsilon)}{\epsilon} \ln(\theta)$

Experimental Evaluation

